

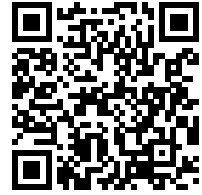
Name:

Worksheet: L03 – Search

CSCI-534: Robot Planning & Manipulation

Spring 2020

<http://www.neil.dantam.name/rpm/B03-search.pdf>



1. **Search Domains – Automobile Navigation:** Pose navigation from Denver to Seattle as a search / planning problem:
 - (a) What is the state space?
 - (b) What is the start state?
 - (c) What are the goal state(s)?
 - (d) What is the transition function?

Name:

2. **Iterative Deepening:** Solve the 3-peg, 2-disk Tower of Hanoi problem via Iterative Deepening Search:

3. **Bidirectional Search:** Solve the 3-peg, 2-disk Tower of Hanoi problem via Bidirectional Search:

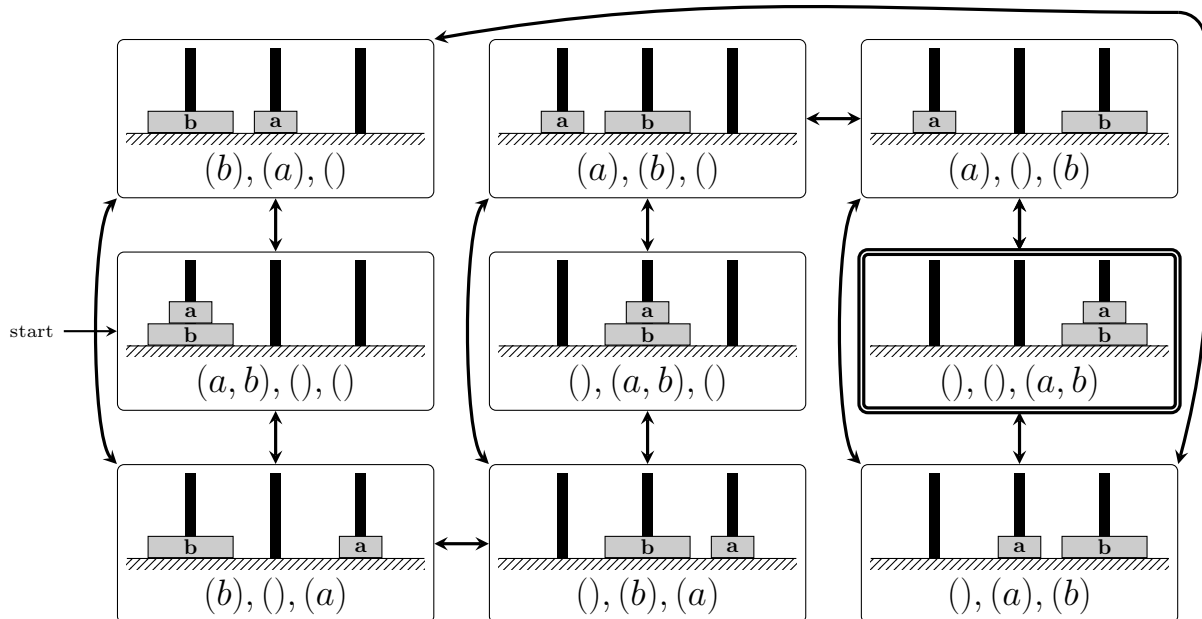


Figure 1: Transition Diagram for 3-peg, 2-disk Tower of Hanoi Problem